## Note

# A Second-Order Property of Spline Functions with One Free Knot 

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#### Abstract

We are concerned with an approximation problem by polynomial spline functions with one free knot. Our main concern is a second-order property of the problem with respect to the knot. We show that every spline function satisfying Braess's alternation condition is nearly optimal. © 1994 Academic Press, Inc.


## 1. Introduction

We deal with a Tchebycheff approximation problem of a prescribed continuous function $f(t)$ by polynomial spline functions with one free knot:

$$
\begin{gather*}
\operatorname{minimize} \quad S(x):=\max \{|f(t)-F(x, t)| ; t \in[0,1]\}  \tag{1}\\
F(x, t)=\sum_{j=0}^{n} x_{j} t^{j}+x_{n+1}(t-\xi)_{+}^{n} \\
x=\left(x_{0}, x_{1}, \ldots, x_{n+1}, \xi\right) \in R^{n+3} . \tag{2}
\end{gather*}
$$

In the following, we put $0=\xi_{0} \leq \xi_{1}=\xi \leq \xi_{2}=1$ and we assume that $n \geq 3$. Braess [1, Cor. 3.5] gave a necessary condition for $F\left(x^{*}, t\right)$ to be a local best approximation ( $S\left(x^{*}\right) \leq S(x)$ on some neighborhood of $x^{*}$ ). His condition asserts that the error function $r(t):=f(t)-F\left(x^{*}, t\right)$ alternates at least $n+2(q-p)-1$ times in some interval $\left[\xi_{p}, \xi_{q}\right]$. The aim of this paper is to show that every spline function which satisfies Braess' condition is nearly optimal in the sense that

$$
\begin{equation*}
0 \leq S^{\prime \prime}\left(x^{*} ; y\right) \leq+\infty \quad \text { for all } y \in R^{n+3} \text { s.t. } S^{\prime}\left(x^{*} ; y\right)=0 \tag{3}
\end{equation*}
$$

where $S^{\prime}\left(x^{*} ; y\right)$ denotes the directional derivatives of $S(x)$ in the direction $y$ and

$$
\begin{equation*}
S^{\prime \prime}\left(x^{*} ; y\right):=\lim _{\theta \rightarrow+0} \frac{S\left(x^{*}+\theta y\right)-S\left(x^{*}\right)-\theta S^{\prime}\left(x^{*} ; y\right)}{\theta^{2}} . \tag{4}
\end{equation*}
$$

When the limit in (4) does not exist, we denote the upper limit by $\bar{S}^{\prime \prime}\left(x^{*} ; y\right)$.

## 2. Second-Order Property

First, we explain our notation. We denote by $F_{x}$ and $F_{x x}$ the gradient vector and the Hesse matrix of $F$ w.r.t. $x$, respectively. We denote by $T(x)$ the set of all extreme points of the error function, that is, $T\left(x^{*}\right):=$ $\left\{t \in[0,1] ;|r(t)|=S\left(x^{*}\right)\right\}$. A vector $y$ is said to be critical if $S^{\prime}\left(x^{*} ; y\right)=0$.

Next, we remark that Braess's condition is equivalent to that there exist extreme points $0 \leq t_{1} \leq \cdots \leq t_{n+4} \leq 1$ and $\lambda_{1}, \ldots, \lambda_{n+4} \geq 0$ not all zero such that

$$
\begin{equation*}
\sum_{i=1}^{n+4} \lambda_{i} \sigma\left(t_{i}\right) F_{x}\left(x^{*}, t_{i}\right)=0 \tag{5}
\end{equation*}
$$

where $\sigma(t)$ denotes the sign of the error function. This fact can be proved by Carathéodory's theorem, Cramer's formula and Karlin-Ziegler's theorem [5, Thm. 1 and 2].

Theorem 1. Suppose that condition (5) is satisfied at $x^{*}$. Then

$$
\begin{equation*}
y^{\mathrm{T}}\left(\sum_{i=1}^{n+4} \lambda_{i} \sigma\left(t_{i}\right) F_{x x}\left(x^{*}, t_{i}\right)\right) y=0 \tag{6}
\end{equation*}
$$

for any critical direction $y \in R^{n+3}$.
Proof. It follows from (2) that condition (5) amounts to

$$
\begin{gather*}
\sum_{i=1}^{n+4} \lambda_{i} \sigma\left(t_{i}\right) t_{i}^{k}=0, k=0, \ldots, n ;  \tag{7}\\
\sum_{i=1}^{n+4} \lambda_{i} \sigma\left(t_{i}\right)\left(t_{i}-\xi\right)_{+}^{k}=0, \quad k=n-1, n .
\end{gather*}
$$

Hence we have

$$
\begin{equation*}
y^{\mathrm{T}}\left(\sum_{i=1}^{n+4} \lambda_{i} \sigma\left(t_{i}\right) F_{x x}\left(x^{*}, t_{i}\right)\right) y=n(n-1) x_{n+1}^{*} y_{n+2}^{2} \sum_{i=1}^{n+4} \lambda_{i} \sigma\left(t_{i}\right)\left(t_{i}-\xi\right)_{+}^{n-2} \tag{8}
\end{equation*}
$$

for any $y$. Therefore (6) is trivial when $x_{n+1}^{*}=0$. When $x_{n+1}^{*} \neq 0,(6)$ is easily derived in the case where $\xi \leq t_{3}$ or $t_{n+2} \leq \xi$. In the case of $t_{3}<\xi<t_{n+2}$, it can be shown that zero vector is the unique critical direction. Indeed, we see by Karlin-Ziegler's theorem that all $(n+3) \times$ ( $n+3$ )-submatrices of the coefficient matrix of (5) are non-singular. Hence all $\lambda_{i}$ 's are positive. On the other hand, it holds for any critical direction $y$ that

$$
\begin{equation*}
0=S^{\prime}\left(x^{*} ; y\right)=\max \left\{-\sigma(t) F_{x}\left(x^{*}, t\right) y ; t \in T\left(x^{*}\right)\right\} \tag{9}
\end{equation*}
$$

see, e.g., Girsanov [4, Ex. 7.5]. Hence, we have

$$
\begin{equation*}
\sigma\left(t_{i}\right) F_{x}\left(x^{*}, t_{i}\right) y \geq 0, \quad i=1, \ldots, n+4 \tag{10}
\end{equation*}
$$

Combining (5) and (10), we have $\lambda_{i} \sigma\left(t_{i}\right) F_{x}\left(x, t_{i}\right) y=0$ for all $i$. Since $\operatorname{rank}\left\{F_{x}\left(x^{*}, t_{i}\right) ; i=1, \ldots, n+4\right\}=n+3$, we get that $y=0$.

Theorem 2. Suppose that Braess's condition is satisfied at $x^{*}$. Then

$$
\begin{equation*}
0 \leq \bar{S}^{\prime \prime}\left(x^{*} ; y\right) \leq+\infty \tag{11}
\end{equation*}
$$

for any critical direction $y$. Moreover, if the error function is expanded into Taylor series as

$$
\begin{equation*}
r(t)=\alpha(t-\tau)^{k}+o\left(|t-\tau|^{k}\right) \quad \text { for some } \alpha \neq 0, k>0 \tag{12}
\end{equation*}
$$

at its zero points, then $0 \leq S^{\prime \prime}\left(x^{*} ; y\right) \leq+\infty$.
Proof. Let $y$ be any critical direction. It follows from Theorem 1 that

$$
\begin{equation*}
-\sigma(\tau) y^{T} F_{x x}\left(x^{*}, \tau\right) y \geq 0 \tag{13}
\end{equation*}
$$

for some $\tau \in T\left(x^{*}\right)$ such that $F_{x}\left(x^{*}, \tau\right) y=0$; see the argument after (10). Next, we put

$$
\begin{equation*}
u(t, \sigma):=S\left(x^{*}\right)-\sigma\left\{f(t)-F\left(x^{*}, t\right)\right\}, \quad v(t, \sigma):=\sigma F_{x}\left(x^{*}, t\right) y \tag{14}
\end{equation*}
$$

and we denote by $\mathscr{T}_{0}$ the set of all $(t, \sigma) \in[0,1] \times\{1,-1\}$ for which there
exists a sequence $\left(t_{n}, \sigma_{n}\right) \in[0,1] \times\{1,-1\}$ converging to $(t, \sigma)$ such that

$$
\begin{equation*}
u\left(t_{n}, \sigma_{n}\right)>0 \forall n, \quad \lim _{n \rightarrow+\infty}-\frac{v\left(t_{n}, \sigma_{n}\right)}{u\left(t_{n}, \sigma_{n}\right)}=+\infty \tag{15}
\end{equation*}
$$

We define a function $E:[0,1] \times\{1,-1\} \rightarrow[-\infty,+\infty]$ as follows:

$$
E(t, \sigma):= \begin{cases}\sup \left\{\begin{array}{l}
\left.\lim \sup \frac{v\left(t_{n}, \sigma_{n}\right)^{2}}{4 u\left(t_{n}, \sigma_{n}\right)} ;\left\{\left(t_{n}, \sigma_{n}\right)\right\} \text { satisfies }(15)\right\} \\
\\
\text { if }(t, \sigma) \in \mathscr{F}_{0}
\end{array}\right.  \tag{16}\\
0, & \text { if } u(t, \sigma)=v(t, \sigma)=0 \text { and }(t, \sigma) \notin \mathscr{F}_{0} \\
-\infty, & \text { otherwise }\end{cases}
$$

Then it follows from Theorem 2.2. in Kawasaki [6] that

$$
\begin{equation*}
\bar{S}^{\prime \prime}(x ; y)=\max \left\{-\frac{1}{2} \sigma(t) y^{\mathrm{T}} F_{x x}(x, t) y+E(t, \sigma(t)) ; F_{x}\left(x^{*}, t\right) y=0\right\} \tag{17}
\end{equation*}
$$

Since $u(\tau, \sigma(\tau))=v(\tau, \sigma(\tau))=0$, we have $0 \leq E(t, \sigma(t)) \leq+\infty$. Hence,

$$
\begin{equation*}
-\sigma(\tau) y^{\mathrm{T}} F_{x x}\left(x^{*}, \tau\right) y+2 E(\tau, \sigma(\tau)) \geq 0 \tag{18}
\end{equation*}
$$

Combining (17) and (18), we get (11). Furthermore, it was shown in Theorem 4.3 of [6] that $\bar{S}^{\prime \prime}(x ; y)=S^{\prime \prime}(x ; y)$ if $r(t)$ satisfies the assumption (12).

We close this paper with noting Mulansky's results [7]. Recently, Mulansky improved Braess's condition by utilizing Cromme's results $[2,3]$ on a tangent cone. Mulansky's condition is in general superior to Braess' condition. However, in our simple context, Mulansky's condition coincides with Braess' condition, because the tangent cone is a subspace.

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